Magnetorotational Instability and Simulations

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Disks: the incomplete list

Galactic disk	spiral	
	elliptical	NGC 4278
Supermassive BH	Quasar	3C 273
	Seyfert	MCG -6-30-15
	LINER	NGC 4258
	LLAGN	Sgr A*
	TDE	Swift J1644+57



Disks: the incomplete list

Stellar mass BH	microquasar	GRS 1915+ 105
	gamma-ray burst	long bursts?
Neutron star	LMXB	Aql X-1
	НМХВ	Cyg X-1
	gamma-ray burst	short bursts?
White dwarf	dwarf nova	SS Cyg
	nova	RS Oph
Protostar	protoplanetary	HL Tau
	debris	Fomahaut
Planet	protolunar disk	Earth/moon
	planetary rings	Saturn



Keplerian disks

- What is a Keplerian disk?
- A disk of material that obeys Kepler's laws of motion due to the dominance of the central massive body
- The azimuthal and angular velocity of a fluid parcel with a distance R from the center are

$$v_{\phi} = \sqrt{\frac{GM}{R}} \quad \Omega = \sqrt{\frac{GM}{R^3}}$$

Keplerian disks

- Hydrostatic equilibrium: the gradient of the pressure equals the gravity $\rho = \rho_0 \exp(-\Omega^2 z^2/2c_s^2) \equiv \rho_0 \exp(-z^2/2H^2)$
- ► C_s is the isothermal sound speed, and the characteristic scale height *H* is defined as $H = c_s/\Omega$, and then $H/R = c_s/v_K$
- > Thin disk approximation requires $H \ll R$, which means that the local rotating speed is much larger than the sound speed

a model disks

Shakura & Sunyaev(1973), Lynden-Bell & Pringle (1974)

 \blacktriangleright Ignore external torques, infall/winds, variation in α

- \blacktriangleright Molecular viscosity $u \sim v_{th} \lambda$ is too small for a reasonable accretion rate
- \blacktriangleright Turbulent viscosity is thus introduced $u_t = lpha c_s H$,usually $lpha \leq 1$

• Or in another form $w_{R\phi} = \alpha \rho c_s^2$, the stress tensor $w_{R\phi} = \rho \delta v_R \delta v_\phi - \frac{B_R B_\phi}{4\pi}$

a model disks

 Radial profile of the surface density using α disk model , Hueso & Guillot (2005)



Turbulence in Disks

- What generates turbulence?
- Possibilities:
 - magnetorotational instability (linear)
 - gravitational instability
 - zombie vortex instability (unique in PPDs)
 - subcritical baroclinic instability (PPDs)
 - vertical shear instability (PPDs)



- Balbus & Hawley(1991)
- A powerful *linear* instability that displays enormous growth rates
- Ideal MHD model is applied for MRI (frozen-in, infinite conductivity)

► We use local Cartesian coordinate corotating with the disk





Physical interpretation: two fluid element sitting on a magnetic field line in analogy to two masses in orbit on a spring



Dispersion relation of MRI

$$\omega^4 - \omega^2 [2k^2 v_A^2 + \kappa^2] + k^2 v_A^2 [k^2 v_A^2 - 2q\Omega^2] = 0$$

Fixed Epicyclic frequency is given by $\kappa^2 = 2(2-q)\Omega^2$

- Critical wavenumber
$$k_c^2 = 2q\Omega^2/v_A^2$$
 $q = -d\ln\Omega/d\ln R$

All MRI modes are incompressible

Rayleigh Criterion: accretion disks with angular momentum increasing outward are linearly stable (q<=2, with no magnetic field)</p>

 $d(R^2\Omega)/dR > 0$

MRI instability criterion

 $d\Omega/dR < 0$

 \blacktriangleright Also $k < k_c$ or $\lambda > \lambda_c$

Fast growing mode is the most unstable mode, also known as channel mode: $k_{max}^2 v_A^2 = \frac{q}{4} (4-q) \Omega^2$

Simulations: from the beginning

- Why do we simulate?
- To understanding MHD turbulence as an angular momentum transport process
- To study the nonlinear evolution or nonlinear regime of the MRI as it grows
- To explore the conditions under which MHD turbulence occurs

Simulations: from the beginning

- Catetogories
- -2D or 3D
- -local or global
- -stratified or unstratified
- -compressible or incompressible
- -ideal MHD limit or dissipation MHD (viscosity, resistivity)
- -zero magnetic flux, weak magnetic flux or strong magnetic flux

Simulations: codes and algorithms

- ZEUS (Stone & Norman 1992; Fromang et al. 2007I, II)
- PENCIL CODE (Brandenburg et al. 1995)
- ATHENA(Stone et al. 2008)
- PLUTO Godnunov (Mignone et al. 2007; Flock et al. 2011)
- NIRVANA-III(Ziegler 2004,2008)
- RAMSES (Teyssier 2002; Fromang et al. 2006)
- SNOOPY (publicly available)

Simulations: from the beginning



- ▶ Bai & Stone (2013)
- isosurface blue to red
- streamlines white to dark white

Simulations: formalism

Ideal magnetohydrodynamic(MHD) equatinos

$$\partial_t \boldsymbol{v} + \boldsymbol{v} \cdot \nabla \boldsymbol{v} = -\frac{1}{\rho} \nabla (P + \frac{B^2}{8\pi}) + \frac{(\boldsymbol{B} \cdot \nabla)\boldsymbol{B}}{4\pi\rho} - 2\boldsymbol{\Omega} \times \boldsymbol{v}$$

 $+2q\Omega^2 x \boldsymbol{e}_x - \Omega^2 z \boldsymbol{e}_z$

$$\frac{\partial \boldsymbol{B}}{\partial t} = \nabla \times (\boldsymbol{v} \times \boldsymbol{B})$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \boldsymbol{v}) = 0$$

Simulations: shearing box system

- Originated with Hill(1878)
- Local 3D MHD simulations of accretion disk (Hawley et al. 1995)
- It only studies a local patch of the disk in Cartesian form
- Only consider the radial component of the gravity (unstratified)
- Ignore buoyancy effects
- Steady state: a uniform shear flow with $v_0 = -q\Omega x e_y$

Simulations: shearing box system Uniform shearing flow as XA background V=- 2RXY \cap

Simulations: shearing box system

The computational domain is surrounded by identical domains moving with a fixed shear velocity



Simulations: shearing box system

Boundary conditions are very important



Simulations: Numerical scheme

- Average physical quantities over volume or over time and volume to avoid random noise
- Fourier decomposition for the power spectrum
- ► Lagrangian wavenumber $k_x = \frac{2\pi n_x}{L_x}$ $k_y = \frac{2\pi n_y}{L_y}$ $k_z = \frac{2\pi n_z}{L_z}$
- Eulerian wavenumber

$$k_x(t) = \frac{2\pi n_x}{L_x} + q\Omega k_y t$$

Simulations: numerical scheme

- Two important dimensionless ratios for initial configurations
- The plasma parameter

$$\beta = \frac{8\pi P_0}{B_0^2}$$

- \blacktriangleright Box size and wavelength ratio $~L_z/\lambda_c$
- \blacktriangleright λ_c is the critical wave length of the fast mode

$$\lambda_c=rac{2\pi}{k_c}\qquad \lambda_c=2\pi\sqrt{16/15}|m{v}_A|/\Omega$$
 for Keplerian disk

Simulations: unstratified



Contour plots of perturbed velocity δv_y which is the difference between actual velocity v_y and the background shearing flow (Hawley et al. 1995)

Simulations: basic results

- An axial magnetic field and toroidal magnetic field both lead to turbulence(with no assumption other than a weak magnetic field)
- It is magnetic field, rather than hydrodynamics, that sustains the angular momentum transport
- The resulting turbulence is nonlinear and nonisotropic

Simulations: basic results

- ▶ Vertical field: $\alpha = 0.2 0.7$
- Foroidal field: $\alpha = 0.02 0.08$
- Simulation results converge when there is a net magnetic flux
- Channel modes break up in 3D simulation
- The total stress is mostly correlated with the magnetic pressure, rather than the gas pressure

Simluations:zero net vertical magnetic flux

Prandtl number is
$$Pm = \frac{Rm}{Re}$$
 $R_m = \frac{ul}{\eta}$ $R_e = \frac{ul}{\nu}$

- Turbulent activity is an increasing function of the magnetic Prandtl number Pm (Fromang et al. 2007II)
- Turbulence disappears when the Prandtl number falls below a critical value Pm_c

Simluations:stratified



- ▶ Bai & Stone (2013)
- Time history of mass weighted Maxwell (solid) and Reynolds (dashed) stresses from simulations.
- The behavior of the MRI turbulence strongly depends on β_0

Summary

- MRI is a significant mechanism to transport angular momentum in accretion disks
- When the dissipation coefficients are small enough not to affect its linear stage, the nonlinear development of the MRI leads to MHD turbulence
- Angular momentum transport can be initiated and sustained by the presence of a weak magnetic field

Summary

- The turbulence is subsonic and the Maxwell stress dominates the Reynolds stress by a factor of a few
- The value of α ranges from 10⁻³ to a few times 10⁻¹ depending on the magnetic field strength

Thank you

